

## 2.10 The law of total probability and Bayes' rule

- ◆ Definition 2.11. For some positive integer  $k$ , let the sets  $B_1, B_2, \dots, B_k$  be such that

1.  $S = B_1 \cup B_2 \cup \dots \cup B_k$ ,

2.  $B_i \cap B_j = \emptyset$  if  $i \neq j$

Then the collection of sets  $\{B_1, B_2, \dots, B_k\}$  is said to be a "partition" of  $S$ .

- ◆ If  $A$  is any subset of  $S$ , and  $\{B_1, B_2, \dots, B_k\}$  is a partition of  $S$ ,  $A$  can be "decomposed" as:

$$A = (A \cap B_1) \cup (A \cap B_2) \cup \dots \cup (A \cap B_k)$$

\* See the Venn Diagram

- ◆ *Theorem 2.8. (The law of total probability) Assume that  $\{B_1, B_2, \dots, B_k\}$  is a partition of  $S$  such that  $P(B_i) > 0$  for  $i=1, \dots, k$ . Then for any event  $A$*

$$P(A) = \sum_{i=1, \dots, k} P(A|B_i)P(B_i)$$

- Proof: apply the additive law
- Sometimes, it's easier to calculate  $P(A|B_i)$  for a suitably chosen partition than to compute  $P(A)$  directly.

- ◆ *Theorem 2.9. (Bayes' Rule) Assume  $\{B_1, B_2, \dots, B_k\}$  is a partition of  $S$  such that  $P(B_i) > 0$  for  $i=1, 2, \dots, k$ . Then*

$$P(B_j | A) = \frac{P(A | B_j)P(B_j)}{\sum_{i=1}^k P(A | B_i)P(B_i)}$$

- ◆ Example 2.23. (An electronic fuse) 5 production lines produce fuses at the same production rate, with 2% defect rate except line 1 with 5% defect rate. A customer tested three fuses and one of them failed. What is:

$$P(\text{the lot was produced in line 1} | \text{the data}) = ?$$

$$P(\text{the lot was produced in one of lines 2-4} | \text{the data}) = ?$$

- ◆ HW. Some of the exercises 2.98~116
- ◆ Keywords: the law of total probability; Bayes rule

## 2.11 Numerical events and random variables

- ◆ Events of major interest are “numerical events”
- ◆ Define a variable  $Y$  that is a function of the sample points in  $S$
- ◆  $\{\text{All sample points where } Y=a\}$  is the numerical event assigned to number  $a$ .
- ◆ The sample space  $S$  can be partitioned into mutually exclusive sets of points assigned to the same value of  $Y$
- ◆ Definition 2.12. A “random variable” is a real-valued function for which the domain is a sample space.
- ◆ Convention: We let  $y$  denote an observed value of  $Y$ .  
Then  $P(Y=y) = \sum\{P(E_i) : i \text{ such that } E_i \text{ is assigned to } y\}$ . Formal definition comes later...
- ◆ Example 2.24. Tossing two coins.  $Y = \#$  of heads. The sample points in  $S$ ?  $Y(E_i) = ?$  Sample points corresponding to  $\{Y=y\}$ ? What is  $P(Y=y)$  for each value of  $y$ ?

## 2.12 Random sampling

- ◆ Population vs. sample (=observations of the values of random variables)
- ◆ Sampling with/without replacement affect probabilities of outcomes
- ◆ Design of experiment is the method of sampling
- ◆ Definition 2.13. In sampling  $n$  elements from a population with  $N$  elements, if the sampling is conducted in such a way that each of  $\binom{N}{n}$  samples has an equal probability of being selected, the sampling is said to be “random” and the result is said to be a “random sample”
- ◆ How to do random sampling?
  - Low-tech method (e.g. drawing tickets from a jar after shaking it)
  - The random number table (Table 12)
  - Use computer (In R, run `sample(1:1000, 100)`)
- ◆ Sometimes we don't want a completely random sample

## 3 Discrete Random Variables and Their Probability Distributions

### 3.1 Basic definition

- ◆ Definition 3.1 A random variation  $Y$  is said to be “discrete” if it can assume only a finite or countably infinite number of distinct values.
- ◆ Knowledge of the probability distributions for random variables associated with common types of experiments will eliminate the need for solving the sample problems over and over again.

### 3.2 The probability distribution for a discrete random variable

- ◆ You have to know the difference between  $Y$  and  $y$ .
- ◆  $(Y=y)$  = “the set of all points in  $S$  assigned the value  $y$  by the random variable  $Y$ ”
- ◆ Definition 3.2 “ $P(Y=y)$ ” or “ $p(y)$ ” is defined as the sum of the probabilities of all sample points in  $S$  that are assigned the value  $y$ .  $p(y)$  is sometimes called the “probability function” for  $Y$
- ◆ Definition 3.3 The “probability distribution” for a discrete variable  $Y$  can be represented by a formula, table, or graph that provides  $p(y)=P(Y=y)$  for all  $y$ .
- ◆ Note  $p(y) \geq 0$  for all  $y$ . Assume  $p(y)=0$  for any values  $y$  not explicitly assigned a positive value.
- ◆ Example 3.1 Find the probability distribution for  $Y=\#$  of women in two workers randomly selected from 3 men and 3 women workers. Interpret the result. Also derive table, graph, and formula for  $p(y)$ .
- ◆ Theorem 3.1 For any discrete probability distribution, the following holds:
  1.  $0 \leq p(y) \leq 1$  for all  $y$
  2.  $\sum_y p(y) = 1$
- ◆ A “simulation study” would give a relative frequency histogram that is similar to the probability distribution
- ◆ HW. Some of the exercises 3.1~9
- ◆ Keywords:  $P(Y=y)=p(y)$ ; probability distribution

### 3.3 The expected value of a random variable or a function of a random variable

- ◆ Definition 3.4 For a discrete random variable  $Y$  with the probability function  $p(y)$ , the “expected value” of  $Y$ ,  $E(Y)$  is defined to be

$$E(Y) = \sum_y yp(y)$$

- ◆ If  $p(y)$  is an accurate characterization of the population frequency distribution, then  $E(Y)=\mu$ , the population mean
- ◆ This definition is consistent with the definition of the mean of a set of measurements (Definition 1.1)
- ◆ What about the mean of  $Y^2$ ? The mean of  $(Y-\mu)^2$ ?

- ◆ *Theorem 3.2 Let  $Y$  be a discrete random variable with probability function  $p(y)$  and  $g(y)$  be a real-valued function of  $Y$ . Then the expected value of  $g(Y)$  is given by*

$$E[g(Y)] = \sum_y g(y)p(y)$$

- Note this is not a definition
- Proof: The trick is to define  $G=g(Y)$  that takes on values  $g_1, \dots, g_m$  and express  $P(G=g_i)=p^*(g_i)$  in terms of  $p(y_i)$

- ◆ Definition 3.5 The variance of a random variable  $Y$  is defined to be

$$V(Y) = E[(Y-\mu)^2].$$

The “standard deviation” of  $Y$  is the positive square root of  $V(Y)$ .

- ◆ If  $p(y)$  is an accurate characterization of the population frequency distribution, then  $V(Y) = \sigma^2$  is the population variance and  $\sigma$  is the population SD.
- ◆ Example 3.2. Find the mean, variance and standard deviation of  $Y$  in the above example.
- ◆ In the following theorems, we assume  $Y$  is a discrete random variable with probability function  $p(y)$

- ◆ *Theorem 3.3 Let  $Y$  be a discrete random variable with probability function  $p(y)$ . For any constant  $c$ ,  $E(c)=c$ .*
- ◆ *Theorem 3.4. Let  $Y$  be a discrete random variable with probability function  $p(y)$ . For a function  $g(Y)$  of  $Y$  and a constant  $c$ ,  $E[cg(Y)] = cE[g(Y)]$ .*
- ◆ *Theorem 3.5. Let  $Y$  be a discrete random variable with probability function  $p(y)$ . For functions  $g_1(Y), g_2(Y), \dots, g_k(Y)$  of  $Y$ ,*  

$$E[g_1(Y)+g_2(Y)+\dots+g_k(Y)]=E[g_1(Y)]+E[g_2(Y)]+\dots+E[g_k(Y)].$$
- ◆ *Theorem 3.6. Let  $Y$  be a discrete random variable with probability function  $p(y)$ . Then,*  

$$V(Y) = \sigma^2 = E[(Y-\mu)^2] = E(Y^2) - \mu^2.$$

- This makes variance computation of example 3.2 easier.

- ◆ Example 3.4 The expected daily cost of two machines A and B.
  
- ◆ HW. Some of the exercises 3.10~24
- ◆ Keywords:  $E(Y)$ ;  $V(Y)$ ;  $E(g(Y))$